

```

accept(2)                                bind(2)

NAME          bind - bind a name to a socket
SYNOPSIS      #include <sys/types.h>
              #include <sys/socket.h>
int accept(int s, struct sockaddr *addr, int addrlen);

DESCRIPTION    The argument s is a socket that has been created with socket(3N) and bound to an address with bind(3N), and that is listening for connections after a call to listen(3N). The accept() function extracts the first connection on the queue of pending connections, creates a new socket with the properties of s, and allocates a new file descriptor, ns, for the socket. If no pending connections are present on the queue and the socket is not marked as non-blocking, accept() blocks the caller until a connection is present. If the socket is marked as non-blocking and no pending connections are present on the queue, accept() returns an error as described below. The accept() function uses the netconfig(4) file to determine the STREAMS device file name associated with s. This is the device on which the connect indication will be accepted. The accepted socket, ns, is used to read and write data to and from the socket that connected to ns; it is not used to accept more connections. The original socket (s) remains open for accepting further connections.

The argument addr is a result parameter that is filled in with the address of the connecting entity as it is known to the communications layer. The exact format of the addr parameter is determined by the domain in which the communication occurs.

The argument addrlen is a value-result parameter. Initially, it contains the amount of space pointed to by addr; on return it contains the length in bytes of the address returned.

The accept() function is used with connection-based socket types, currently with SOCK_STREAM. It is possible to select(3C) or poll(2) a socket for the purpose of an accept() by selecting or polling it for a read. However, this will only indicate when a connect indication is pending; it is still necessary to call accept().

RETURN VALUE   On success, these system calls return a nonnegative integer that is a file descriptor for the accepted socket. On error, -1 is returned, and errno is set appropriately.

ERRORS         accept() will fail if:
              EBADF           The descriptor is invalid.
              EINTR            The accept attempt was interrupted by the delivery of a signal.
              EMFILE           The per-process descriptor table is full.
              ENODEV           The protocol family and type corresponding to s could not be found in the netconfig file.
              ENOMEM          There was insufficient user memory available to complete the operation.
              EPROTO          A protocol error has occurred; for example, the STREAMS protocol stack has not been initialized or the connection has already been released.
              EWOULD_BLOCK   The socket is marked as non-blocking and no connections are present to be accepted.

SEE ALSO       poll(2), bind(3N), connect(3N), listen(3N), select(3C), socket(3N), netconfig(4), attributes(5), socket(5)
              unlink(2), socket(3N), attributes(5), socket(5)

NOTES          Binding a name in the UNIX domain creates a socket in the file system that must be deleted by the caller when it is no longer needed (using unlink(2)). The rules used in name binding vary between communication domains.

```

```

close(2)           dup(2)

NAME      close - close a file descriptor
NAME      dup, dup2 - duplicate a file descriptor

SYNOPSIS
#include <unistd.h>
int close(int fd);

DESCRIPTION
close() closes a file descriptor, so that it no longer refers to any file and may be reused. Any record locks (see fentl(2)) held on the file it was associated with, and owned by the process, are removed (regardless of the file descriptor that was used to obtain the lock). If fd is the last file descriptor referring to the underlying open file description (see open(2)), the resources associated with the open file description are freed; if the file descriptor was the last reference to a file which has been removed using unlink(2), the file is deleted.

RETURN VALUE
close() returns zero on success. On error, -1 is returned, and errno is set appropriately.

ERRORS
EBADF
fd isn't a valid open file descriptor.

EINTR
The close() call was interrupted by a signal; see signal(7).

EIO
An I/O error occurred.

ENOSPC, EDQUOT
On NFS, these errors are not normally reported against the first write which exceeds the available storage space, but instead against a subsequent write(2), sync(2), or close(2).


```

**NAME**

**dup, dup2** – duplicate a file descriptor

**SYNOPSIS**

```
#include <unistd.h>
```

**DESCRIPTION**

```
int dup(int oldfd);
int dup2(int oldfd, int newfd);
```

**dup()** and **dup2()** create a copy of the file descriptor *oldfd*.

**dup()** uses the lowest-numbered unused descriptor for the new descriptor.

**dup2()** makes *newfd* be the copy of *oldfd*, closing *newfd* first if necessary, but note the following:

- \* If *oldfd* is not a valid file descriptor, then the call fails, and *newfd* is not closed.
- \* If *oldfd* is a valid file descriptor, and *newfd* has the same value as *oldfd*, then **dup2()** does nothing, and returns *newfd*.

After a successful return from **dup()** or **dup2()**, the old and new file descriptors may be used interchangeably. They refer to the same open file description (see **open(2)**) and thus share file offset and file status flags; for example, if the file offset is modified by using **lseek(2)** on one of the descriptors, the offset is also changed for the other.

The two descriptors do not share file descriptor flags (the close-on-exec flag). The close-on-exec flag (**FD\_CLOEXEC**; see **tentl(2)**) for the duplicate descriptor is off.

**RETURN VALUE**

**dup()** and **dup2()** return the new descriptor, or -1 if an error occurred (in which case, *errno* is set appropriately).

**ERRORS**

**EBADF**
*oldfd* isn't an open file descriptor, or *newfd* is out of the allowed range for file descriptors.

**EBUSY**
(Linux only) This may be returned by **dup2()** during a race condition with **open(2)** and **dup()**.

**EINTR**
The **dup2()** call was interrupted by a signal; see **signal(7)**.

**EMFILE**
The process already has the maximum number of file descriptors open and tried to open a new one.

**SEE ALSO**

**close(2), fcntl(2), open(2)**



ipv6/socket(7)

getc/fgets/putc/fputs(3)

**NAME** ipv6, AF\_INET6 – Linux IPv6 protocol implementation

**SYNOPSIS**

```
#include <sys/types.h>
#include <sys/socket.h>
#include <netinet/in.h>
```

**DESCRIPTION**

Linux 2.2 optionally implements the Internet Protocol, version 6. This man page contains a description of the IPv6 basic API as implemented by the Linux kernel and glibc 2.1. The interface is based on the BSD sockets interface; see `socket(7)`.

The IPv6 API aims to mostly compatible with the `ip(7)` v4 API. Only differences are described in this man page.

To bind an `AF_INET6` socket to any process the local address should be copied from the `inet6addr_any` variable which has `inet6_addr` type. In static initializations `IN6ADDR_ANY_INIT` may also be used, which expands to a constant expression. Both of them are in network order.

IPv4 connections can be handled with the v6 API by using the v4-mapped-on-v6 address type; thus a program only needs only to support this API type to support both protocols. This is handled transparently by the address handling functions in libc.

IPv4 and IPv6 share the local port space. When you get an IPv4 connection or packet to a IPv6 socket its source address will be mapped to v6 and it will be mapped to v6.

**Address Format**

```
struct sockaddr_in6 {
    uint16_t sin6_family; /* AF_INET6 */
    uint16_t sin6_port; /* port number */
    uint32_t sin6_flowinfo; /* IPv6 flow information */
    struct in6_addr sin6_addr; /* IPv6 address */
    uint32_t sin6_scope_id; /* Scope ID (new in 2.4) */
};

struct in6_addr {
    unsigned char   s6_addr[16]; /* IPv6 address */
};
```

`sin6_family` is always set to `AF_INET6`; `sin6_port` is the protocol port (see `sin_port` in `ip(7)`); `sin6_flowinfo` is the IPv6 flow identifier; `sin6_addr` is the 128-bit IPv6 address. `sin6_scope_id` is an ID of depending of on the scope of the address. It is new in Linux 2.4. Linux only supports it for link scope addresses, in that case `sin6_scope_id` contains the interface index (see `netdevice(7)`)

**RETURN VALUES**

`getc()`, `getc()` and `getchar()` return the character read as an `unsigned char` cast to an `int` or `EOF` on end of file or error.

`fgetc()` returns `'\n'` on success, and `NULL` on error or when end of file occurs while no characters have been read. `fpputc()`, `putc()` and `putchar()` return the character written as an `unsigned char` cast to an `int` or `EOF` on error.

`fputs()` returns a nonnegative number on success, or `EOF` on error.

**SEE ALSO**

`read(2)`, `write(2)`, `ferror(3)`, `fgetwc(3)`, `fgets(3)`, `fread(3)`, `fseek(3)`, `getline(3)`, `getchar(3)`, `scanf(3)`, `ungetwc(3)`, `wire(2)`, `fflush(3)`, `fopen(3)`, `fpputwc(3)`, `fseek(3)`, `fwrite(3)`, `gets(3)`, `putwchar(3)`, `scanf(3)`, `unlockd_stdio(3)`

**SEE ALSO**

`emsg(3)`, `ip(7)`

**NOTES**

The `sockaddr_info` structure is bigger than the generic `sockaddr`. Programs that assume that all address types can be stored safely in a `struct sockaddr_storage` need to be changed to use `struct sockaddr_storage` for that instead.

**SEE ALSO**

`SP-Klausur Manual-Auszug`

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listen(2) `listen(2)`

opendir/readdir(3) `opendir/readdir(3)`

**NAME** `listen` – listen for connections on a socket

**SYNOPSIS**

```
#include <sys/types.h>      /* See NOTES */
#include <sys/socket.h>
```

**int listen(int sockfd, int backlog);**

**DESCRIPTION**

`listen` marks the socket referred to by `sockfd` as a passive socket, that is, as a socket that will be used to accept incoming connection requests using `accept(2)`.

The `sockfd` argument is a file descriptor that refers to a socket of type **SOCK\_STREAM** or **SOCK\_SEQPACKET**.

The `backlog` argument defines the maximum length to which the queue of pending connections for `sockfd` may grow. If a connection request arrives when the queue is full, the client may receive an error with an indication of **ECONNREFUSED** or, if the underlying protocol supports retransmission, the request may be ignored so that a later reattempt at connection succeeds.

**RETURN VALUE**

On success, zero is returned. On error, `-1` is returned, and `errno` is set appropriately.

**ERRORS**

**EADDRINUSE** Another socket is already listening on the same port.

**EBADF** The argument `sockfd` is not a valid descriptor.

**ENOTSOCK** The argument `sockfd` is not a socket.

**NOTES**

To accept connections, the following steps are performed:

1. A socket is created with `socket(2)`.
2. The socket is bound to a local address using `bind(2)`, so that other sockets may be `connect(2)`ed to it.
3. A willingness to accept incoming connections and a queue limit for incoming connections are specified with `listen()`.
4. Connections are accepted with `accept(2)`.

If the `backlog` argument is greater than the value in `/proc/sys/net/core/somaxconn`, then it is silently truncated to that value; the default value in this file is 128.

**EXAMPLE**

See `bind(2)`.

**SEE ALSO**

`accept(2)`, `bind(2)`, `connect(2)`, `socket(2)`, `socket(7)`

**NAME** `opendir` – open a directory / `readdir` – read a directory

**SYNOPSIS**

```
#include <sys/types.h>
#include <dirent.h>
```

**DIR \*opendir(const char \*name);**

**int closedir(DIR \*dirp);**

**struct dirent \*readdir(DIR \*dir);**

**DESCRIPTION** `opendir`

The `opendir()` function opens a directory stream corresponding to the directory `name`, and returns a pointer to the directory stream. The stream is positioned at the first entry in the directory.

**RETURN VALUE**

The `opendir()` function returns a pointer to the directory stream. On error, `NULL` is returned, and `errno` is set appropriately.

**DESCRIPTION** `closedir`

The `closedir()` function closes the directory stream associated with `dirp`. A successful call to `closedir()` also closes the underlying file descriptor associated with `dirp`. The directory stream descriptor `dirp` is *not available after this call*.

**RETURN VALUE**

The `closedir()` function returns `0` on success. On error, `-1` is returned, and `errno` is set appropriately.

**DESCRIPTION** `readdir`

The `readdir()` function returns a pointer to a dirent structure representing the next directory entry in the directory stream pointed to by `dir`. It returns `NULL` on reaching the end-of-file or if an error occurred. It is safe to use `readdir()` inside threads if the pointers passed as `dir` are created by distinct calls to `opendir()`.

The data returned by `readdir()` is overwritten by subsequent calls to `readdir()` for the same directory stream.

The `dirent` structure is defined as follows:

```
struct dirent {
    long           d_ino;          /* inode number */
    char           d_name[256];    /* filename */
};
```

**RETURN VALUE**

On success, `readdir()` returns a pointer to a `dirent` structure. (This structure may be statically allocated; do not attempt to `free(3)` it.)

If the end of the directory stream is reached, `NULL` is returned and `errno` is not changed. If an error occurs, `NULL` is returned and `errno` is set appropriately. To distinguish end of stream and from an error, set `errno` to zero before calling `readdir()` and then check the value of `errno` if `NULL` is returned.

**ERRORS**

**EACCES** Permission denied.

**ENOENT** Directory does not exist, or `name` is an empty string.

**ENOTDIR** `name` is not a directory.

```

pthread_cond(3)                         pthread_cond(3)

NAME
    pthread_cond_init,      pthread_cond_destroy,   pthread_cond_signal,
    pthread_cond_wait,     pthread_cond_timedwait - operations on conditions

SYNOPSIS
#include <pthread.h>

pthread_cond_t cond = PTHREAD_COND_INITIALIZER;

int pthread_cond_init(pthread_cond_t *cond, pthread_condattr_t *cond_attr);

int pthread_cond_signal(pthread_cond_t *cond);

int pthread_cond_broadcast(pthread_cond_t *cond);

int pthread_cond_wait(pthread_cond_t *cond, pthread_mutex_t *mutex);

int pthread_cond_timedwait(pthread_cond_t *cond, pthread_mutex_t *mutex, const struct timespec
*abstime);

int pthread_cond_destroy(pthread_cond_t *cond);

```

**DESCRIPTION**  
A condition (short for “condition variable”) is a synchronization device that allows threads to suspend execution and relinquish the processor until some predicate on shared data is satisfied. The basic operations on conditions are signal the condition (when the predicate becomes true), and wait for the condition, suspending the thread execution until another thread signals the condition.

A condition variable must always be associated with a mutex, to avoid the race condition where a thread prepares to wait on a condition variable and another thread signals the condition just before the first thread actually waits on it.

**pthread\_cond\_init** initializes the condition variable *cond*, using the condition attributes specified in *cond\_attr*, or default attributes if *cond\_attr* is **NULL**. The Linux Threads implementation supports no attributes for conditions, hence the *cond\_attr* parameter is actually ignored.

Variables of type **pthread\_cond\_t** can also be initialized statically, using the constant **PTHREAD\_COND\_INITIALIZER**.

**pthread\_cond\_signal** restarts one of the threads that are waiting on the condition variable *cond*. If no threads are waiting on *cond*, nothing happens. If several threads are waiting on *cond*, exactly one is restarted, but it is not specified which.

**pthread\_cond\_broadcast** restarts all the threads that are waiting on the condition variable *cond*. Nothing happens if no threads are waiting on *cond*.

**pthread\_cond\_wait** atomically unlocks the *mutex* (as per **pthread\_unlock\_mutex**) and waits for the condition variable *cond* to be signaled. The thread execution is suspended and does not consume any CPU time until the condition variable is signaled. The *mutex* must be locked by the calling thread on entrance to **pthread\_cond\_wait**. Before returning to the calling thread, **pthread\_cond\_wait** re-acquires *mutex* (as per **pthread\_lock\_mutex**).

Unlocking the mutex and suspending on the condition variable is done atomically. Thus, if all threads always acquire the mutex before signaling the condition, this guarantees that the condition cannot be

**pthread\_cond\_timedwait** atomically unlocks *mutex* and waits on *cond*, as **pthread\_cond\_wait** does, but it also bounds the duration of the wait. If *cond* has not been signaled within the amount of time specified by *abstime*, the mutex *mutex* is re-acquired and **pthread\_cond\_timedwait** returns the error **ETIMEOUT**. The *abstime* parameter specifies an absolute time, with the same origin as **time(2)** and **gettimeofday(2)**: an *abstime* of 0 corresponds to 00:00:00 GMT, January 1, 1970.

**pthread\_cond\_destroy** destroys a condition variable, freeing the resources it might hold. No threads must be waiting on the condition variable on entrance to **pthread\_cond\_destroy**. In the Linux Threads implementation, no resources are associated with condition variables, thus **pthread\_cond\_destroy** actually does nothing except checking that the condition has no waiting threads.

**CANCELLATION**  
**pthread\_cond\_wait** and **pthread\_cond\_timedwait** are cancellation points. If a thread is cancelled while suspended in one of these functions, the thread immediately resumes execution, then locks again the *mutex* argument to **pthread\_cond\_wait** and **pthread\_cond\_timedwait**, and finally executes the cancellation. Consequently, cleanup handlers are assured that *mutex* is locked when they are called.

**ASYNC-SIGNAL SAFETY**  
The condition functions are not async-signal safe, and should not be called from a signal handler. In particular, calling **pthread\_cond\_signal** or **pthread\_cond\_broadcast** from a signal handler may deadlock the calling thread.

**RETURN VALUE**  
All condition variable functions return 0 on success and a non-zero error code on error.

**ERRORS**  
**EINVAL** **pthread\_cond\_init**, **pthread\_cond\_signal**, **pthread\_cond\_broadcast**, and **pthread\_cond\_wait** never return an error code.

The **pthread\_cond\_timedwait** function returns the following error codes on error:

**ETIMEOUT**  
the condition variable was not signaled until the timeout specified by *abstime*

**EINTR**  
**pthread\_cond\_timedwait** was interrupted by a signal

The **pthread\_cond\_destroy** function returns the following error code on error:

**EBUSY**  
some threads are currently waiting on *cond*.

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**SEE ALSO**  
**pthread\_condattr\_init(3)**, **pthread\_mutex\_lock(3)**, **pthread\_mutex\_unlock(3)**, **gettimeofday(2)**, **nanosleep(2)**.

```

pthread_create(pthread_exit(3)                                     pthread_mutex(3)

pthread_create/pthread_exit(3)                                     pthread_mutex(3)

NAME
    pthread_create – create a new thread / pthread_exit – terminate the calling thread

SYNOPSIS
    #include <pthread.h>

    int pthread_create(pthread_t * thread, pthread_attr_t * attr, void * (*start_routine)(void *), void *
    args);

    void pthread_exit(void *retval);

DESCRIPTION
    pthread_create creates a new thread of control that executes concurrently with the calling thread. The new thread applies the function start_routine passing it arg as first argument. The new thread terminates either explicitly, by calling pthread_exit(3), or implicitly, by returning from the start_routine function. The latter case is equivalent to calling pthread_exit(3) with the result returned by start_routine as exit code.

    The attr argument specifies thread attributes to be applied to the new thread. See pthread_attr_init(3) for a complete list of thread attributes. The attr argument can also be NULL, in which case default attributes are used: the created thread is joinable (not detached) and has default (non real-time) scheduling policy.

    pthread_exit terminates the execution of the calling thread. All cleanup handlers that have been set for the calling thread with pthread_cleanup_push(3) are executed in reverse order (the most recently pushed handler is executed first). Finalization functions for thread-specific data are then called for all keys that have non-NULL values associated with them in the calling thread (see pthread_key_create(3)). Finally, execution of the calling thread is stopped.

    The retval argument is the return value of the thread. It can be consulted from another thread using pthread_join(3).

RETURN VALUE
    On success, the identifier of the newly created thread is stored in the location pointed by the thread argument, and a 0 is returned. On error, a non-zero error code is returned.

    The pthread_exit function never returns.

ERRORS
    EAGAIN
        not enough system resources to create a process for the new thread.

    EAGAIN
        more than PTHREAD_THREADS_MAX threads are already active.

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SEE ALSO
    pthread_join(3), pthread_detach(3), pthread_attr_init(3),
    pthread_errorcheck(3), PTHREAD_ERRORCHECK_MUTEX_INITIALIZER_NP,
    PTHREAD_ERRORCHECK_MUTEX_INITIALIZER,
    PTHREAD_ERRORCHECK_MUTEX_ERRORCHECK,
    PTHREAD_ERRORCHECK_MUTEX_ERRORCHECK_NP

```

Variables of type `pthread_mutex_t` can also be initialized statically, using the constants `PTHREAD_MUTEX_INITIALIZER` (for fast mutexes), `PTHREAD_ERRORCHECK_MUTEX_INITIALIZER_NP` (for recursive mutexes), and `PTHREAD_ERRORCHECK_MUTEX_INITIALIZER` (for error checking mutexes).

`pthread_mutex_lock` locks the given mutex. If the mutex is currently unlocked, it becomes locked and owned by the calling thread, and `pthread_mutex_lock` suspends the calling thread until the mutex is unlocked by another thread.

If the mutex is already locked by the calling thread, the behavior of `pthread_mutex_lock` depends on the kind of the mutex. If the mutex is of the “fast” kind, the calling thread is suspended until the mutex is unlocked, thus effectively causing the calling thread to deadlock. If the mutex is of the “error checking” kind, `pthread_mutex_lock` returns immediately with the error code `EDEADLK`. If the mutex is of the “recursive” kind, `pthread_mutex_lock` succeeds and returns immediately, recording the number of times the calling thread has locked the mutex. An equal number of `pthread_mutex_unlock` operations must be

sigaction(2)

pthread\_mutex(3) pthread\_mutex(3) pthread\_mutex(3) sigaction(2)

**NAME** sigaction – POSIX signal handling functions.

**SYNOPSIS**

```
#include <signal.h>
```

**int sigaction(int signum, const struct sigaction \*act, struct sigaction \*oldact);**

**DESCRIPTION**

The **sigaction** system call is used to change the action taken by a process on receipt of a specific signal. *signum* specifies the signal and can be any valid signal except **SIGKILL** and **SIGSTOP**. If *act* is non-null, the new action for signal *signum* is installed from *act*. If *oldact* is non-null, the previous action is saved in *oldact*.

The **sigaction** structure is defined as something like

```
struct sigaction {
    void (*sa_handler)(int signal_number);
    sa_mask;
    int sa_flags;
}
```

*sa\_handler* specifies the action to be associated with *signum* and may be **SIG\_DFL** for the default action. **SIG\_IGN** to ignore this signal, or a pointer to a signal handling function.

*sa\_mask* gives a mask of signals which should be blocked during execution of the signal handler. In addition, the signal which triggered the handler will be blocked, unless the **SA\_NODEFER** or **SA\_NOMASK** flags are used.

performed before the mutex returns to the unlocked state.

**pthread\_mutex\_trylock** behaves identically to **pthread\_mutex\_lock**, except that it does not block the calling thread if the mutex is already locked by another thread (or by the calling thread in the case of a “fast” mutex). Instead, **pthread\_mutex\_trylock** returns immediately with the error code **EBUSY**.

**pthread\_mutex\_unlock** unlocks the given mutex. The mutex is assumed to be locked and owned by the calling thread on entrance to **pthread\_mutex\_unlock**. If the mutex is of the “fast” kind, **pthread\_mutex\_unlock** always returns it to the unlocked state. If it is of the “recursive” kind, it decrements the locking count of the mutex (number of **pthread\_mutex\_lock** operations performed on it by the calling thread), and only when this count reaches zero is the mutex actually unlocked.

On “error checking” mutexes, **pthread\_mutex\_unlock** actually checks at runtime that the mutex is locked on entrance and that it was locked by the same thread that is now calling **pthread\_mutex\_unlock**. If these conditions are not met, an error code is returned and the mutex remains unchanged. “Fast” and “recursive” mutexes perform no such checks, thus allowing a locked mutex to be unlocked by a thread other than its owner. This is non-portable behavior and must not be relied upon.

**pthread\_mutex\_destroy** destroys a mutex object, freeing the resources it might hold. The mutex must be unlocked on entrance. In the Linux Threads implementation, no resources are associated with mutex objects, thus **pthread\_mutex\_destroy** actually does nothing except checking that the mutex is unlocked.

**RETURN VALUE**

**pthread\_mutex\_init** always returns 0. The other mutex functions return 0 on success and a non-zero error code on error.

<b>ERRORS</b>	The <code>pthread_mutex_lock</code> function returns the following error code on error:
<b>EINVAL</b>	If the mutex has not been properly initialized.
<b>EDEADLK</b>	The mutex is already locked by the calling thread ("error checking" mutexes only).
The <code>pthread_mutex_unlock</code> function returns the following error code on error:	
<b>EINVAL</b>	The mutex has not been properly initialized.
<b>EPERM</b>	The calling thread does not own the mutex ("error checking" mutexes only).
The <code>pthread_mutex_destroy</code> function returns the following error code on error:	
<b>EBUSY</b>	An invalid signal was specified. This will also be generated if an attempt is made to change the action for <code>SIGKILL</code> or <code>SIGSTOP</code> , which cannot be caught.
<b>SEE ALSO</b>	<code>kill(1)</code> , <code>kill(2)</code> , <code>killing(2)</code> , <code>pause(2)</code> , <code>sigsetops(3)</code>
<b>sa_flags</b>	Specifies a set of flags which modify the behaviour of the signal handling process. It is formed by the bitwise OR of zero or more of the following:
<b>SA_NOCLDSTOP</b>	If <i>signum</i> is <code>SIGCHLD</code> , do not receive notification when child processes stop (i.e., when child processes receive one of <code>SIGSTOP</code> , <code>SIGSTP</code> , <code>SIGTSTP</code> or <code>SIGTTOU</code> ).
<b>SA_RESTART</b>	Provide behaviour compatible with BSD signal semantics by making certain system calls restartable across signals. Without <code>SA_RESTART</code> the system calls return an error and set <i>errno</i> to <code>EINTR</code> when interrupted by a signal.
<b>RETURN VALUES</b>	<code>sigaction()</code> returns 0 on success; on error, -1 is returned, and <i>errno</i> is set to indicate the error.
<b>ERRORS</b>	<b>EINVAL</b>

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**SEE ALSO** [nthread mutexattr init\(3\)](#) [nthread mutexattr setkind nm\(3\)](#) [nthread cancel\(3\)](#)

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```
stat(2)          stat(2)
```

**NAME** stat, fstat, Istat — get file status

**SYNOPSIS**

```
#include <sys/types.h>
#include <sys/stat.h>
#include <unistd.h>

int stat(const char *path, struct stat *buf);
int fstat(int fd, struct stat *buf);
int Istat(const char *path, struct stat *buf);
```

Feature Test Macro Requirements for glibc (see **feature\_test\_macros(7)**):

```
Istat(): _BSD_SOURCE || _XOPEN_SOURCE >= 500
```

**DESCRIPTION**

These functions return information about a file. No permissions are required on the file itself, but — in the case of **stat()** and **Istat()** — execute (search) permission is required on all of the directories in *path* that lead to the file.

**stat()** stats the file pointed to by *path* and fills in *buf*.

**Istat()** is identical to **stat()**, except that if *path* is a symbolic link, then the link itself is stat-ed, not the file that it refers to.

**fstat()** is identical to **stat()**, except that the file to be stat-ed is specified by the file descriptor *fd*.

All of these system calls return a *stat* structure, which contains the following fields:

```
struct stat {
    dev_t    st_dev;      /* ID of device containing file */
    ino_t    st_ino;      /* inode number */
    mode_t   st_mode;     /* protection */
    nlink_t  st_nlink;    /* number of hard links */
    uid_t    st_uid;      /* user ID of owner */
    gid_t    st_gid;      /* group ID of owner */
    dev_t    st_rdev;     /* device ID (if special file) */
    off_t    st_size;     /* total size, in bytes */
    blksize_t st_blksize; /* blocksize for file system I/O */
    blkcnt_t st_blocks;   /* number of blocks allocated */
    time_t   st_atime;    /* time of last access */
    time_t   st_mtime;    /* time of last modification */
    time_t   st_ctime;    /* time of last status change */
};
```

The *st\_dev* field describes the device on which this file resides.

The *st\_rdev* field describes the device that this file (inode) represents.

The *st\_size* field gives the size of the file (if it is a regular file or a symbolic link) in bytes. The size of a symlink is the length of the pathname it contains, without a trailing null byte.

The *st\_blocks* field indicates the number of blocks allocated to the file, 512-byte units. (This may be smaller than *st\_size*/512 when the file has holes.)

The *st\_blksize* field gives the "preferred" blocksize for efficient file system I/O. (Writing to a file in smaller chunks may cause an inefficient read-modify-rewrite.)

Not all of the Linux file systems implement all of the time fields. Some file system types allow mounting in such a way that file accesses do not cause an update of the *st\_atime* field. (See "noinode" in **mount(8)**.)

The field *st\_atime* is changed by file accesses, for example, by **execve(2)**, **mknod(2)**, **pipe(2)**, **utime(2)** and **read(2)** (of more than zero bytes). Other routines, like **mmap(2)**, may or may not update *st\_atime*.

The field *st\_mtime* is changed by file modifications, for example, by **mknod(2)**, **truncate(2)**, **utime(2)** and **write(2)** (of more than zero bytes). Moreover, *st\_mtime* of a directory is changed by the creation or deletion of files in that directory. The *st\_mtime* field is *not* changed for changes in owner, group, hard link count, or mode.

The field *st\_ctime* is changed by writing or by setting inode information (i.e., owner, group, link count, mode, etc.).

The following POSIX macros are defined to check the file type using the *st\_mode* field:

S_ISREG(m)	is it a regular file?
S_ISDIR(m)	directory?
S_ISCHR(m)	character device?
S_ISBLK(m)	block device?
S_ISFIFO(m)	FIFO (named pipe)?
S_ISLNK(m)	symbolic link? (Not in POSIX.1-1996.)
S_ISSOCK(m)	socket? (Not in POSIX.1-1996.)

**RETURN VALUE**

On success, zero is returned. On error, -1 is returned, and *errno* is set appropriately.

<b>ERRORS</b>	<b>EACCES</b>	Search permission is denied for one of the directories in the path prefix of <i>path</i> . (See also <b>path_resolution(7)</b> .)
	<b>EBADF</b>	<i>fd</i> is bad.
	<b>EFAULT</b>	Bad address.
	<b>ELOOP</b>	Too many symbolic links encountered while traversing the path.
	<b>ENAMETOOLONG</b>	File name too long.
	<b>ENOENT</b>	A component of the path <i>path</i> does not exist, or the path is an empty string.
	<b>ENOMEM</b>	Out of memory (i.e., kernel memory).
	<b>ENOTDIR</b>	A component of the path is not a directory.

**SEE ALSO**

**access(2)**, **chmod(2)**, **chown(2)**, **fstatat(2)**, **readlink(2)**, **utime(2)**, **capabilities(7)**, **symlink(7)**

string(3)

**NAME**      `strcat, strchr, strcmp, strcpy, strdup, strlen, strncat, strncmp, strncpy, strstr, strtok – string operations`

**SYNOPSIS**

```
#include <string.h>
char *strcat(char *dest, const char *src);
Append the string src to the string dest, returning a pointer dest.
char *strchr(const char *s, int c);
Return a pointer to the first occurrence of the character c in the string s.
int strcmp(const char *s1, const char *s2);
Compare the strings s1 with s2. It returns an integer less than, equal to, or greater than zero if s1 is
found, respectively, to be less than, to match, or be greater than s2.
char *strcpy(char *dest, const char *src);
Copy the string src to dest, returning a pointer to the start of dest.
char *strdup(const char *s);
Return a duplicate of the string s in memory allocated using malloc(3).
size_t strlen(const char *s);
Return the length of the string s.
char *strcat(char *dest, const char *src, size_t n);
Append at most n characters from the string src to the string dest, returning a pointer to dest.
int strncmp(const char *s1, const char *s2, size_t n);
Compare at most n bytes of the strings s1 and s2. It returns an integer less than, equal to, or
greater than zero if s1 is found, respectively, to be less than, to match, or be greater than s2.
char *strncpy(char *dest, const char *src, size_t n);
Copy at most n bytes from string src to dest, returning a pointer to the start of dest.
char *strstr(const char *haystack, const char *needle);
Find the first occurrence of the substring needle in the string haystack, returning a pointer to the
found substring.
char *strtok(char *, const char *delim);
Extract tokens from the string s that are delimited by one of the bytes in delim.
```

**DESCRIPTION**

The string functions perform operations on null-terminated strings.